# On the Formal Verification of Open Multi-agent Systems

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## Overview

#### Background:

- plenty of work on model checking Multi-agent Systems [LQR09, GvdM04, KNN<sup>+</sup>08]:
  - () MAS are composed of a finite number of agents given at design time ....
  - 2 and they are described at propositional level (CTL, LTL, ATL, + epistemics, etc.)
- Main task: formal verification of open MAS
  - given a model  $\mathcal{M}_S$  of system S and a formula  $\phi_P$  for property P, does  $\mathcal{M}_S \models \phi_P$ ?
  - open: agents can enter and leave the MAS at run-time [JMS13]
    - \* model checking is appropriate for control-intensive applications...
    - ...but less suited for data-intensive applications (data typically range over infinite domains) [BK08]

#### Motivation:

- auctions, markets, etc.
- (non-probabilistic) diffusion phenomena (how information, ideas, behaviors spread in networks of agents similarly to epidemics)
  - ★ SIR model for epidemics
- Social Network Analysis (SNA) [Jac08, EK10]

#### 4 Key contribution:

- verification of open MAS is decidable ...
- ... whenever the system is bounded
- application to the case study SIR model for epidemics

# The SIR Model

- Influential network diffusion model [EK10, Jac08]
- Individuals are liable to go through three different stages during an epidemic:
  - first, each agent is susceptible to be infected
  - she may actually get infected at a certain point
  - finally she will eventually recover
- Verifiable behaviours:
  - every agent either remains susceptible or will eventually become infected if she is continuously in contact with someone infected
  - if an agent knows that she is connected to some infected agent, then she will part at some point in the future
  - if an agent gets infected, then all agents that are connected to her will eventually know this fact.
- Results:
  - (non-stochastic) SIR model can be captured within open MAS
  - ▶ specifications such as (1)-(3) above can be (expressed and) model-checked

# Challenges & Research Questions

Challenges:

- Multi-agent System, but ...
- ... the number of agents is **potentially infinite**
- the system is open: agents can join in or leave at run-time
- states have a relational structure
- the state space is infinite in general!
  - $\Rightarrow$  the model checking problem cannot be tackled by standard techniques.

#### Research questions:

- Is the verification of open MAS decidable?
- 9 if not, can we identify relevant fragments that are reasonably well-behaved?

# Open Multi-agent Systems

Technical Results

• Open Multi-agent Systems (OMAS) as a flexible and rich framework for SNA. Intuition: encoding an agent's information structure as a database.

FO-CTLK<sub>x</sub> as a specification language:

 $\forall x, y(K_x(Inf(y) \land N(x, y)) \to AF \neg N(x, y))$ 

if an agent knows that she is connected to some infected agent, then she will part at some point in the future

- epistemic operators indexed to terms in the language
- quantification on those indexes

We leverage on recent results on data-aware systems to tackle model checking [BPL14, HCG<sup>+</sup>13, MCD14].

Main result: abstraction techniques to reduce the MC problem to the finite case.

Gase study: modelling and verification of the SIR model.

#### Data-aware Systems Preliminaries on databases

- Recent paradigm in Service-Oriented Computing [CH09].
- Motto: let's give data and processes the same relevance!
  - the data content shapes the actions of processes
- Agents' local states are represented as databases.
  - ▶ a database schema is a finite set  $D = \{P_1/q_1, ..., P_n/q_n\}$  of relation symbols  $P_i$  with arity  $q_i \in \mathbb{N}$
  - a (database) instance on a domain U is a mapping D associating each symbol  $P_i$  with a finite  $q_i$ -ary relation on U
  - ▶ the active domain adom(D) is the set of all elements  $u \in U$  appearing in some  $D(P_i)$
  - ▶ the disjoint union  $D \oplus D'$  of D-instances D and D' is the  $(D \cup D')$ -instance s.t.
    - ★  $D \oplus D'(P) = D(P)$
    - $\star D \oplus D'(P') = D'(P)$
  - $\mathcal{D}(U)$  is the set of all  $\mathcal{D}$ -instances on U
- Intuition: networks (graphs on agents) are represented as first-order structures

# Open Multi-agent Systems

Agents

Hereafter we assume

- a finite number of **agent types**  $T_0, \ldots, T_k$ 
  - as well as a **possibly infinite** set  $Ag_T$  of agent names for each type T
  - ▶ the interpretation domain U includes  $Ag = \bigcup_{type T} Ag_T$

# Definition (Agent)

An agent 
$$a_T = \langle \mathcal{D}_T, Act_T, Pr_T \rangle$$
 of type T

records information according to the local database schema  $\mathcal{D}_{\mathcal{T}}$ 

including a dedicated unary predicate  ${\it N}$  to represent the network structure

and performs the actions  $\alpha(\vec{x})$  in  $Act_T \dots$ 

... according to the local protocol function  $Pr_T : \mathcal{D}_T(U) \mapsto 2^{Act_T(U)}$ 

- the number of agent types is finite:
  - $\Rightarrow$  typically it is possible to specify the relevant agent types at design time.
- the number of agents is infinite:
  - it is much more difficult to know how many agents of each type will appear during the system's execution.
- the setting is reminiscent of the **interpreted system semantics** for MAS [FHMV95], ... ... but here the local state of each agent is relational.

## Example: the SIR Model I

In the basic setting we have a unique type of agent.

- the interpretation domain is U = Ag.
- an agent a includes
  - a local db schema

$$\mathcal{D}_{\textit{a}} = \{\textit{Sus}/1,\textit{Inf}/1,\textit{Rec}/1,\textit{N}/1\}$$

a set of actions

$$Act_a = \{con(ag), disc(ag), skip\}$$

- the protocol Pr<sub>a</sub> is such that
  - ★ disc(b) ∈  $Pr_a(l_a)$  whenever  $b \in l_a(N)$
  - ★ {skip, con(b)} ⊆  $Pr_a(I_a)$  for all  $I_a \in D_a(U)$

We might want to assess the impact of health workers on epidemics.

- we consider a new type  $T_H$  and set  $Ag_H$  of agent names
- a health worker h has database  $\mathcal{D}_h$  and actions  $Act_h$  defined as for standard agents.
  - while the protocol Pr<sub>h</sub> is such that
    - ★  $disc(b) \in Pr_h(I_h)$  only if  $b \in I_h(N)$  and  $Inf(h) \in I_h$

The framework is rich enough to accommodate several versions of the SIR model.

## Open Multi-agent Systems OMAS

Agents interact, thus generating OMAS.

### Definition (Global State)

Given a finite subset  $A \subseteq Ag$  of agents  $a_i = \langle \mathcal{D}_i, Act_i, Pr_i \rangle$ , for  $i \leq n$ , a global state is a tuple  $s = \langle l_0, \ldots, l_n \rangle$  of instances  $l_i \in \mathcal{D}_i(U)$ .

- at every state only finitely many agents are active
  - if  $s = \langle l_{a_0}, \ldots, l_{a_n} \rangle$  then  $ag(s) = \{a_0, \ldots, a_n\}$  is the set of agents active in s
- key difference w.r.t. interpreted (parametric) systems: global states may be tuples of different lengths

### Definition (OMAS)

An OMAS  $\mathcal{P} = \langle Ag, U, I, \rightarrow \rangle$  describes

- the evolution of a **possibly infinite** group Ag of agents ...
- from an initial global state  $s_0 \in I \dots$
- according to the transition relation  $s \xrightarrow{\alpha(\vec{u})} s'$

where  $\alpha(\vec{u})$  contains an action for each agent active in s

OMAS are infinite-state systems in general

## Example: the SIR Model II

The SIR OMAS  $\mathcal{P} = \langle Ag \cup Ag_H, I, \tau \rangle$  with health workers is defined as

- *I* is the set of states where at least one agent is infected (this rules out trivial models).
- $\rightarrow$  is the transition relation s.t.  $s \xrightarrow{\alpha(\vec{u})} s'$  whenever
  - a susceptible agent a might get infected if she is in contact with an infected agent: if Sus(a) ∈ l<sub>a</sub> and for some b ∈ l<sub>a</sub>(N), Inf(b) ∈ l<sub>b</sub>, then either Sus(a) ∈ l'<sub>a</sub> or Inf(a) ∈ l'<sub>a</sub>
  - an infected agent a non-deterministically recovers: if Inf(a) ∈ l<sub>a</sub>, then either Inf(a) ∈ l'<sub>a</sub> or Rec(a) ∈ l'<sub>a</sub>
  - a recovered agent a does not fall ill again: if Rec(a) ∈ l<sub>a</sub> then Rec(a) ∈ l'<sub>a</sub>
  - the consistency of the agents' information is assumed to be preserved.

▶ ...

# The Specification Language: FO-CTLK<sub>x</sub>

• First-order version of CTL + knowledge:

 $\varphi \quad ::= \quad R(t_1, \dots, t_c) \mid t = t' \mid \neg \varphi \mid \varphi \rightarrow \varphi \mid \forall x \varphi \mid AX\varphi \mid A\varphi U\varphi \mid E\varphi U\varphi \mid K_a\varphi \mid K_x\varphi$ 

Epistemic operators indexed to terms in the language.

• OMAS  $\mathcal{P}$  satisfies formula  $\varphi$  in state s for assignment  $\sigma$ , iff

$$\begin{array}{lll} (\mathcal{P},s,\sigma) \models R(\vec{t}) & \text{iff} & \langle \sigma(t_1),\ldots,\sigma(t_c) \rangle \in D_s(R) \\ (\mathcal{P},s,\sigma) \models t = t' & \text{iff} & \sigma(t) = \sigma(t') \\ (\mathcal{P},s,\sigma) \models \forall x \varphi & \text{iff} & \text{for all } u \in adom(s), (\mathcal{P},s,\sigma_u^x) \models \varphi \\ (\mathcal{P},s,\sigma) \models A X \varphi & \text{iff} & \text{for all } runs r, r(0) = s \text{ implies } (\mathcal{P},r(1),\sigma) \models \varphi \\ (\mathcal{P},s,\sigma) \models A \varphi U \varphi' & \text{iff} & \text{for all } runs r, r(0) = s \text{ implies } (\mathcal{P},r(k),\sigma) \models \varphi' \text{ for some } k \ge 0, \\ & and (\mathcal{P},r(k'),\sigma) \models \varphi \text{ for all } 0 \le k' < k \\ (\mathcal{P},s,\sigma) \models K_a \varphi & \text{iff} & \text{for all states } s', s \sim_a s' \text{ implies } (\mathcal{P},s',\sigma) \models \varphi \\ (\mathcal{P},s,\sigma) \models K_x \varphi & \text{iff} & \text{for all states } s', s \sim_a s' \text{ implies } (\mathcal{P},s',\sigma) \models \varphi \\ \end{array}$$

where  $s \sim_a s'$  iff  $a \in ag(s)$ ,  $a \in ag(s')$ , and  $s_a = s'_a$ .

- Active-domain semantics, but...
  - ...we can refer to individuals that no longer exist
  - the number of states is infinite in general

# The Specification Language: FO-CTLK<sub>x</sub>

each agent goes through the susceptible-infected-recovered cycle

 $\forall x A(Sus(x)UA(Inf(x)URec(x)))$ 

if an agent knows that she is connected to some infected agent, then she will part at some point in the future

$$\forall \mathbf{x}, y (K_{\mathbf{x}}(Inf(y) \land N(\mathbf{x}, y)) \to AF \neg N(\mathbf{x}, y))$$

if an agent gets infected, then all agents that are connected to her will eventually know this fact.

$$\forall y (Inf(y) \rightarrow (AF \forall \mathbf{x} (N(\mathbf{x}, y) \rightarrow K_{\mathbf{x}} Inf(y))))$$

- ∀xK<sub>x</sub>φ expresses dynamically the joint knowledge of φ for all active agents in a given state, i.e., the standard, static epistemic formula Eφ = Λ<sub>a∈Ag</sub> K<sub>a</sub>φ.
- epistemic formulas are vacuously true for agents not in the active domain of the state considered:
  - $a \notin ag(s)$  implies  $(P, s, \sigma) \models K_a \phi$  for all formulas  $\phi$

# Verification of AC-MAS

- Model-checking problem: given
  - an OMAS  $\mathcal{P}_S$  (for a system S)
  - an FO-CTLK<sub>x</sub> sentence  $\phi_P$  (representing property P)

we check that

$$\mathcal{P}_{S} \models \phi_{P}$$

- Problem: the infinite domain U may generate infinitely many states!
- Investigated solution: can we simulate the concrete values in *U* with a finite set of abstract symbols?

## Abstraction: Isomorphism and Bisimulation

• two states *s*, *s'* are isomorphic, or *s*  $\simeq$  *s'*, if they share the same relational structure

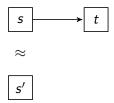
	D(R)				D'	( <i>R</i> )
$A_1$	а	b	$\sim$	$A_1$	1	2
$A_2$	b	с	<u> </u>	$A_2$	2	3
$A_3$	d	е		<i>A</i> <sub>3</sub>	4	5

- i.e., there is a bijection  $\iota : adom(s) \cup ag(s) \mapsto adom(s') \cup ag(s')$  such that
  - $\iota$  preserves the type of agents
  - for every tuple  $\vec{u}$  and agent  $a_i \in ag(s)$ ,

$$\vec{u} \in D_i(P) \Leftrightarrow \iota(\vec{u}) \in D'_{\iota(i)}(P)$$

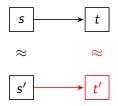
# Abstraction: Isomorphism and Bisimulation

- two states s, s' are bisimilar, or  $s \approx s'$ , if
  - $\bigcirc s\simeq s'$
  - 2 the simulation and transition relations commute



# Abstraction: Isomorphism and Bisimulation

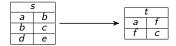
- two states s, s' are bisimilar, or  $s \approx s'$ , if
  - $\bigcirc s\simeq s'$
  - 2 the simulation and transition relations commute



- if  $s \to t$  then there is t' s.t.  $s' \to t'$ ,  $s \oplus t \simeq s' \oplus t'$ , and  $t \approx t'$
- the other direction holds as well
- ▶ similar conditions hold for the epistemic relation ~a

# Uniformity

• the behaviour of OMAS is **independent** from data not explicitly named in the system description.

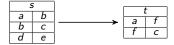


<i>s</i> ′				
1	2			
2	С			
4	5			

t	t'				
$\left[ 1 \right]$	6				
6	С				

# Uniformity

 the behaviour of OMAS is independent from data not explicitly named in the system description.





- OMAS are uniform:
  - for  $s, t, s' \in S$  and  $t' \in D(U)$ ,  $s \to t$  and  $s \oplus t \simeq s' \oplus t'$  imply  $s' \to t'$
- Uniformity holds in many cases of interest [CH09, BPL14, HCG<sup>+</sup>13, MCD14].

# Bisimulation and Equivalence w.r.t. FO-CTLK<sub>x</sub>

Bisimilar OMAS satisfy the same FO-CTLK $_{\times}$  formulas (provided some assumption on the cardinalities of the domains)

### Theorem

#### Consider

- bisimilar OMAS  $\mathcal P$  and  $\mathcal P'$
- an FO-CTLK<sub>x</sub> formula  $\varphi$

#### lf

$$|U'| \ge 2 \cdot \sup_{s \in \mathcal{P}} \{ |adom(s) \cup ag(s)| \} + |vars(\varphi)|$$

2) for every type T, 
$$|Ag_T'| \ge 2 \sup_{s \in \mathcal{P}} \{|ag_T(s)|\} + |vars(arphi)|$$

$$|U| \geq 2 \cdot \sup_{s' \in \mathcal{P}'} \{|adom(s') \cup ag(s)|\} + |vars(\varphi)|$$

• for every type 
$$T$$
,  $|Ag_T| \ge 2 \sup_{s' \in \mathcal{P}'} \{|ag_T(s')|\} + |vars(\varphi)|$ 

then

$$\mathcal{P}\models\varphi\quad \textit{iff}\quad \mathcal{P}'\models\varphi$$

#### Can we apply this result to obtain finite abstraction?

# Bounded Models and Finite Abstractions

- an OMAS  $\mathcal{P}$  is *b*-bounded iff for all  $s \in \mathcal{P}$ ,  $|adom(s) \cup ag(s)| \leq b$ .
- bounded systems can still be infinite!

#### Theorem

#### Consider

a b-bounded OMAS  $\mathcal{P}$  on an infinite domain U

an FO-CTLK<sub>x</sub> formula  $\varphi$ 

Given a finite domain U' s.t.

- $|U'| \ge 2b + \max\{|vars(\varphi)|, b \cdot N_{Ag}\}$
- 2 for every type T,  $|Ag'_T| \ge 2b + \max\{|vars(\varphi)|, b \cdot N_{Ag}\}$

there exists a finite abstraction  $\mathcal{P}'$  of  $\mathcal{P}$  s.t.  $\mathcal{P}'$  is bisimilar to  $\mathcal{P}$ . In particular,

$$\mathcal{P} \models \varphi \quad iff \quad \mathcal{P}' \models \varphi$$

- $\Rightarrow$  Under specific circumstances (namely boundedness), we can model check an infinite-state OMAS by verifying its finite abstraction.
  - Boundedness is a natural assumption on the SIR model.
    - For a sufficiently large *b*, we can simulate a *b*-bounded SIR model with a domain U' s.t. |U'| = 3b.

# Conclusions

#### • Results:

- bisimulation and finite abstraction for open Multi-agent Systems
- we are able to model check OMAS w.r.t. FO-CTLK<sub>x</sub> ...
- ... however, our results hold only for bounded systems
- this class covers many interesting systems (AS programs, [CH09, HCG<sup>+</sup>11, BPL14])
- including the SIR model

#### • Future Work:

- constructive techniques for finite abstraction
- model checking techniques for finite-state systems are effective on OMAS?
- how to perfom the boundedness check?

# Questions?

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