

And-Or Tableaux for Fixpoint Logics with Converse: LTL, CTL, PDL, CPDL

Rajeev Goré

(Pietro Abate, Ling Anh Nguyen, Linda Postniece,
Jimmy Thomson, Florian Widmann)

Logic and Computation Group
College of Engineering and Computer Science
The Australian National University
rajeev.gore@anu.edu.au

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A Motivating Example from Business Process Modelling

Banking: rules for ensuring processes meet anti-fraud legislation

Example: rules for granting a request to open a bank account

Rule 1: A risk assessment (ra) must eventually be carried out for each request to open a bank account (ro)

Rule 2: A request to open a bank account (ro) is granted (rog) only if the risk is assessed as low (ral)

Rule 3: A due diligence assessment (dd) must eventually be carried out for each request to open a bank account (ro)

Rule 4: If a person fails due diligence (ddf) then he or she must be blacklisted (bl)

Question: how to check these rules for consistency and sanity?

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Need: a logic which captures temporal notions like “eventually”, “after”, “before” as well as “if then”, “only if” etc.

Fixpoint Logics: Linear Temporal Logic

Syntax: CPL plus “next”, “until”, “before”, “always”, “eventually”

$atom ::= p \mid q \mid r \mid \dots$

$\varphi, \psi ::= atom \mid \neg\varphi \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \varphi \rightarrow \psi$
 $\mid \bigcirc\varphi \mid \varphi \mathcal{U} \psi \mid \varphi \mathcal{B} \psi \mid [F]\varphi \mid \langle F \rangle \varphi$

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Semantics: infinite linear discrete sequence of points s_0, s_1, s_2, \dots

Model: truth value **t** or **f** to each atomic formula at each state s_i

Evaluate CPL formula: at state s_i using truth tables

Evaluate “temporal” formula: using relative order of states

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Model: truth value **t** or **f** to each atomic formula at each state s_i

Evaluate CPL formula: at state s_i using truth tables

Evaluate “temporal” formula: using relative order of states

Satisfiable: true at some state in some sequence

Valid: true in all states of every sequence

Lemma: φ is valid if and only if $\neg\varphi$ is unsatisfiable

LTL: Kripke Semantics for Assigning \mathbf{t} at State s_i

Connective	s_i	s_{i+1}	\dots	s_j	\dots	s_k	s_{k+1}	\dots
<i>next</i>	$\bigcirc p$	p						
<i>Until</i>	$p \mathcal{U} q$	p	\dots	p	\dots	q		
<i>Before</i>	$p \mathcal{B} q, \neg q$	$\neg q$	\dots	$\neg q$	\dots	$\neg q$	$\neg q$	\dots
<i>Before</i>	$p \mathcal{B} q, \neg q$	$\neg q$	\dots	$p, \neg q$	\dots	q		

\mathcal{U} : is “strong” and demands that eventually q is true at some s_k

\mathcal{U} : s_k is the first state after or equal to s_i where q is true

\mathcal{B} : is “weak” since it does not demand eventually q

\mathcal{B} : is “strictly before” since q at s_i is forbidden

LTL: Defined Connectives

<i>Defn</i>	s_i	s_{i+1}	s_{i+2}	s_j	\dots	s_k
$\top := (p \vee \neg p)$	\top	\top	\top	\top	\dots	\top
$\perp := \neg \top$	<i>never true</i>					
$\langle F \rangle \psi := (\top \mathcal{U} \psi)$	$\langle F \rangle \psi$	\top	\top	\top	\dots	ψ
	$\neg \langle F \rangle \psi$	$\neg \psi$	$\neg \psi$	$\neg \psi$	\dots	$\neg \psi$
$[F] \varphi := (\neg \langle F \rangle \neg \varphi)$	$[F] \varphi, \varphi$	φ	\dots	φ	\dots	φ

$\langle F \rangle \psi$: captures “eventually in the Future ψ ”

$[F] \varphi$: captures “always in the Future φ ”

Encoding Our Example from Business Process Modelling

Rule 1: A risk assessment (*ra*) must eventually be carried out for each request to open a bank account (*ro*)

$$[F](ro \rightarrow \langle F \rangle ra)$$

Rule 2: A request to open a bank account (*ro*) is granted (*rog*) only if the risk is low (*ral*)

$$[F](rog \rightarrow ral)$$

Rule 3: A due diligence assessment (*dd*) must eventually be carried out for each request to open a bank account (*ro*)

$$[F](ro \rightarrow \langle F \rangle dd)$$

Rule 4: If a person fails due diligence (*ddf*) then he or she must be blacklisted (*bl*)

$$[F]((dd \wedge ddf) \rightarrow \langle F \rangle bl)$$

Awad et al: An iterative approach to synthesize business process templates from compliance rules. *Inf. Syst.* 37(8): 714-736 (2012)

Fixpoint Logics: PLTL, CTL, LCK, PDL, CTL*, μ -calculus

PLTL: $\varphi \mathcal{U} \psi$ $\leftrightarrow \psi \vee \bigcirc(\varphi \mathcal{U} \psi)$

CTL: $E(\varphi \mathcal{U} \psi)$ $\leftrightarrow \psi \vee EXE(\varphi \mathcal{U} \psi)$

LCK: $\langle C \rangle \psi$ $\leftrightarrow \langle E \rangle \psi \vee \langle E \rangle \langle C \rangle \psi$

PDL: $\langle \alpha^* \rangle \psi$ $\leftrightarrow \psi \vee \langle \alpha \rangle \langle \alpha^* \rangle \psi$

Kripke semantics: involve a base “step-relation” e.g. “next”

Least Fixpoints: “now or after one step”

$\langle F \rangle \varphi$: is least fixpoint $\mu Z.(\varphi \vee \bigcirc Z)$

$[F] \varphi$: is greatest fixpoint $\nu Z.(\varphi \wedge \bigcirc Z)$

Standard Translation: none are first-order definable

Fragments: of monadic second order logic of one successor S1S

The main logical problems and their complexity

Given:

- ▶ a logic $L \in \{LTL, CTL, PDL, \dots\}$
- ▶ a finite set \mathcal{T} of global assumption (TBox) L-formulae
- ▶ a single L-formula φ

Satisfiability: is there an L-model that makes \mathcal{T} true everywhere and makes φ true somewhere

Global logical consequence: for every L-model M , if M makes \mathcal{T} true everywhere then M makes φ true everywhere (glc)

Validity: put $\mathcal{T} = \emptyset$

Counter-models: if φ not a glc of \mathcal{T} then output a model which makes \mathcal{T} true everywhere and φ false somewhere

Complexity: deciding glc is EXPTIME-complete

Why Tableaux?

Tableaux algorithms provide some of the most efficient methods for automated reasoning in non-classical logics

Long history (1979-2010) of attempts to devise tableau algorithms for fixpoint logics without much success

This talk summarises almost seven years of work from 2003-2010 with various people

Modal Tableaux as And-Or Trees (Using NNF)

$$(id) \frac{p; \neg p; X}{}$$

$$(\wedge) \frac{\varphi \wedge \psi; X}{\varphi; \psi; X}$$

$$(\vee) \frac{\varphi \vee \psi; X}{\varphi; X \mid \psi; X}$$

$$(K) \frac{\langle \rangle \varphi_1; \langle \rangle \varphi_2; \dots; \langle \rangle \varphi_k; \Box X; Z}{\mathcal{T}; \varphi_1; X \parallel \mathcal{T}; \varphi_2; X \parallel \dots \parallel \mathcal{T}; \varphi_k; X} \dagger$$

\mathcal{T} is a given finite set of global assumption formulae

X, Y, Z are finite **possibly empty** sets of formulae

$\varphi; X$ stands for a partition of the **non-empty** set $\{\varphi\} \cup X$

\dagger : Z is saturated (contains no top level \wedge, \vee, \Box formulae)

A K-tableau for Y given global assumptions \mathcal{T}

is an inverted (or-branching) tree of nodes with:

1. a root node $\text{nnf}(\mathcal{T}; Y)$
2. and such that all children nodes are obtained from their parent node by instantiating a rule of inference

Propagation: Determining the status of nodes

$$(id) \frac{p; \neg p; X}{} \quad (\wedge) \frac{\varphi \wedge \psi; X}{\varphi; \psi; X} \quad (\vee) \frac{\varphi \vee \psi; X}{\varphi; X \mid \psi; X}$$

$$(K) \frac{\langle \rangle \varphi_1; \langle \rangle \varphi_2; \dots; \langle \rangle \varphi_k; \Box X; Z}{\mathcal{T}; \varphi_1; X \parallel \mathcal{T}; \varphi_2; X \parallel \dots \parallel \mathcal{T}; \varphi_k; X} \dagger$$

Status of every node is initially unexpanded

Status sat if we can apply no rule

Status unsat if we apply (id)

Status changes to open for other rule applications

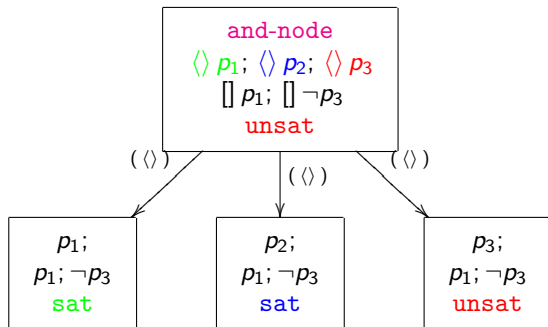
or-node: becomes sat if any child becomes sat and becomes unsat if all children become unsat

and-node: becomes unsat if any child becomes unsat and becomes sat if all children become sat

Example: the And-branching (K)-rule

$$(K) \frac{\langle \varphi_1; \langle \varphi_2; \dots; \langle \varphi_k; \Box X; Z \rangle \rangle}{\mathcal{T}; \varphi_1; X \parallel \mathcal{T}; \varphi_2; X \parallel \dots \parallel \mathcal{T}; \varphi_k; X} \dagger (Z \text{ saturated})$$

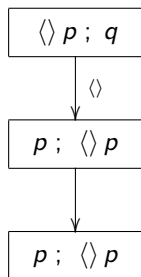
Only one and-or tableau for $\langle p_1; \langle p_2; \langle p_3; \Box p_1; \Box \neg p_3 \rangle \rangle$



Example: Termination Requires Ancestor Loops

$$(K) \frac{\langle \varphi_1; \langle \varphi_2; \dots; \langle \varphi_k; [] X; Z \rangle \rangle}{\mathcal{T}; \varphi_1; X \parallel \mathcal{T}; \varphi_2; X \parallel \dots \parallel \mathcal{T}; \varphi_k; X} \dagger (Z \text{ saturated})$$

The tableau for $\mathcal{T} = \{ \langle p \rangle \}$ and $\varphi := q$ loops!



Solution: check whether new node exists already on the current branch and stop when we see the same node (loop check)

Note: looping nodes return open ... turns to sat at end of algorithm

Soundness, Completeness and Termination

Thm: every and-or tableau (with ancestor loops) is finite

Thm: **any** and-or tableau for $\mathcal{T} \cup \{\neg\varphi_0\}$ returns **unsat** iff φ_0 is glc of \mathcal{T}

Complexity:: Worst-case is 2^{EXPTIME} i.e. $O(2^{2^n})$

Cause: tree tableaux can explore the same node on multiple branches

Optimisations: practical implementations use many optimisations

Tableau Rules for LTL in Smullyan's α - and β -notation

Notation captures abstract “conjunctive” and “disjunctive” notions

α	α_1	α_2
$\varphi \wedge \psi$	φ	ψ
$\varphi B \psi$	$\sim \psi$	$\varphi \vee \bigcirc(\varphi B \psi)$
$[F]\varphi$	φ	$\bigcirc[F]\varphi$

β	β_1	β_2
$\varphi \vee \psi$	φ	ψ
$\varphi U \psi$	ψ	$\varphi \wedge \bigcirc(\varphi U \psi)$
$\langle F \rangle \varphi$	φ	$\bigcirc \langle F \rangle \varphi$

Define: $\sim \psi := NNF(\neg \psi)$

Prop: all instances of $\alpha \leftrightarrow \alpha_1 \wedge \alpha_2$ and $\beta \leftrightarrow \beta_1 \vee \beta_2$ are valid

Assume: that all formulae are in Negation Normal Form

Tableau Rules: only applicable to non-starred formulae

$$(\alpha) \frac{\Gamma; \alpha}{\alpha^*; \Gamma; \alpha_1; \alpha_2} \quad (\beta) \frac{\Gamma; \beta}{\beta^*; \Gamma; \beta_1 \mid \beta^*; \Gamma; \beta_2} \quad (\bigcirc) \frac{\Lambda; \bigcirc\varphi; \bigcirc\Delta}{\varphi; \Delta}$$

where Λ contains only atoms, negated atoms and starred formulae

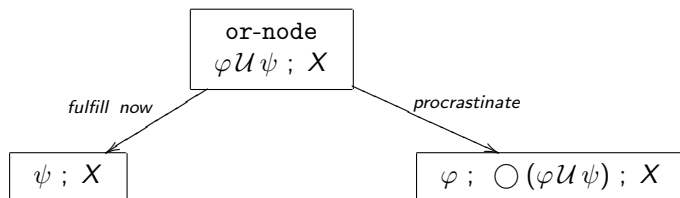
Traditional Multipass Graph Methods (1979-1998)

Phase 1: apply rules to obtain a cyclic graph

Phase 2: using multiple passes, prune inconsistent nodes and nodes that contain eventualities unfulfilled by the current graph

Eventuality: formulae which can be postponed for ever

LTL eventualities: $\varphi \mathcal{U} \psi$ and $\langle F \rangle \varphi := (\top \mathcal{U} \varphi)$



Answer unsat: if root node gets pruned

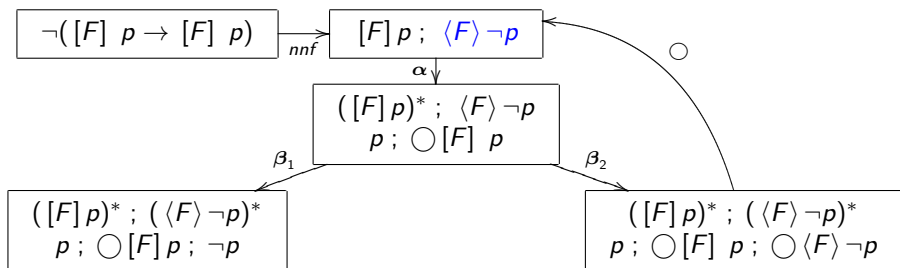
Answer sat: if no pruning possible (all eventualities fulfilled)

Example: is $[F] p \rightarrow [F] p$ LTL-valid ? Phase 1

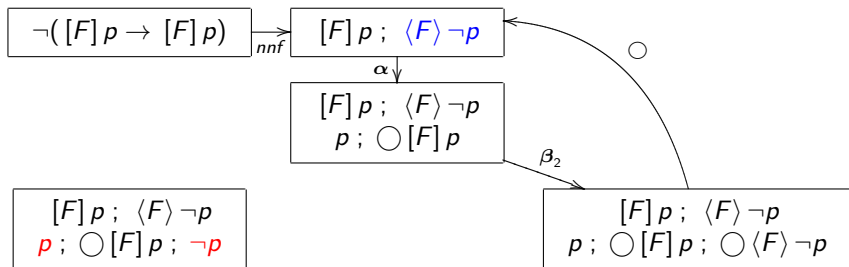
α	α_1	α_2
$[F] \varphi$	φ	$\bigcirc [F] \varphi$

β	β_1	β_2
$\langle F \rangle \varphi$	φ	$\bigcirc \langle F \rangle \varphi$

$$(\bigcirc) \frac{\wedge; \bigcirc \varphi; \bigcirc \Delta}{\varphi; \Delta} \dagger$$



Example: is $[F] p \rightarrow [F] p$ LTL-valid ? Phase 2



Unstar all starred formulae

Prune the node containing $\{p, \neg p\}$

Prune the **root** containing $\langle F \rangle \neg p$ since no path reaches $\neg p$

That is, $[F] p ; \langle F \rangle \neg p$ is not LTL-satisfiable.

Hence $[F] p \rightarrow [F] p$ is LTL-valid.

Properties of the graph multipass tableau method

Worst case complexity: is EXPTIME

Best case complexity: can be better than EXPTIME

Disadvantage: can do unnecessary work

Example: $\langle F \rangle \varphi \wedge \langle F \rangle \Psi$ where Ψ is huge but irrelevant

Ideal: build, prune and check eventualities “on the fly”

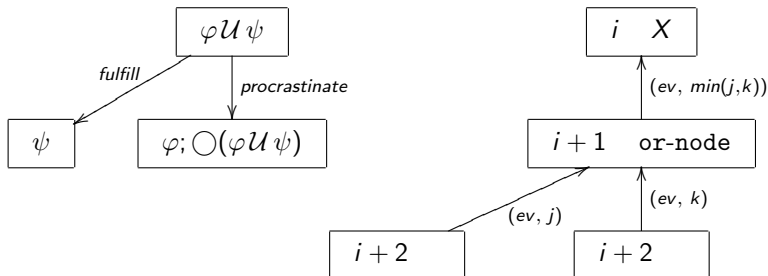
One-pass And-Or Tree Tableaux for LTL (1998)

Use the tree-tableaux for modal logics, with ancestor loops

One pass: build a rooted and-or tree with ancestor cycles and allow nodes to pass up a list of unfulfilled eventualities

Advantage: can explore one branch at a time

Disadvantage: suboptimal (2^{EXPTIME})

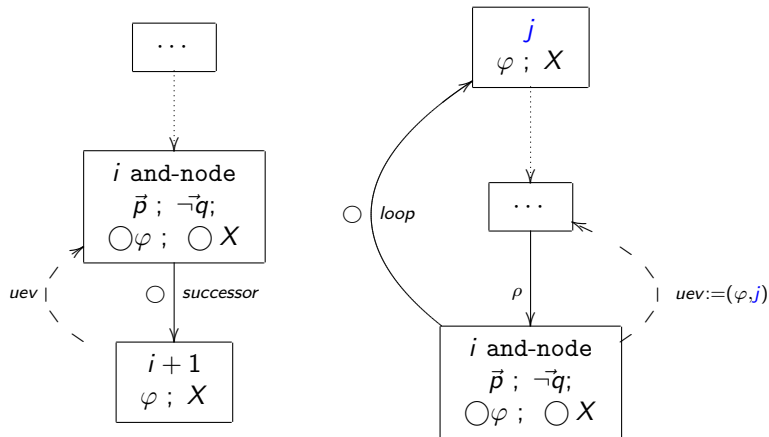


Close: any node at height h with an eventuality $(ev, h+1)$

S. Schwendimann. A new one-pass tableau calculus for PLTL. In *Proc. TABLEAUX'98*, LNAI 1397:277-291. Springer, 1998.

One-pass And-Or Tree Tableaux

Use the tree-tableaux for modal logics, with ancestor loops

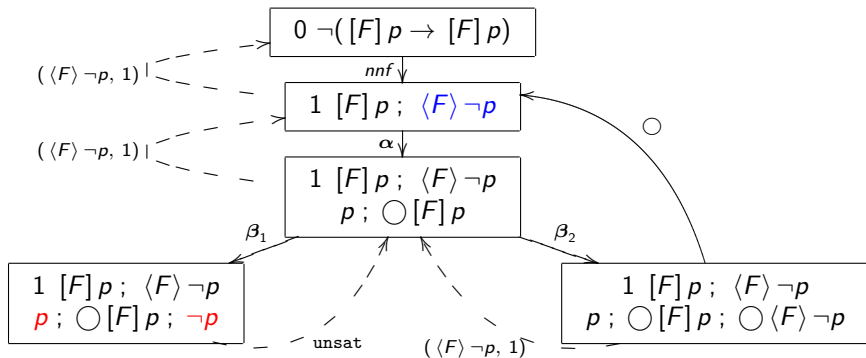


\bigcirc rule: either creates a successor or blocks on an existing ancestor

New: rules now pass back a set of pairs (ev, j) listing blocks

Tree-tableau method for LTL

Use the tree-tableaux for modal logics, with ancestor loops:

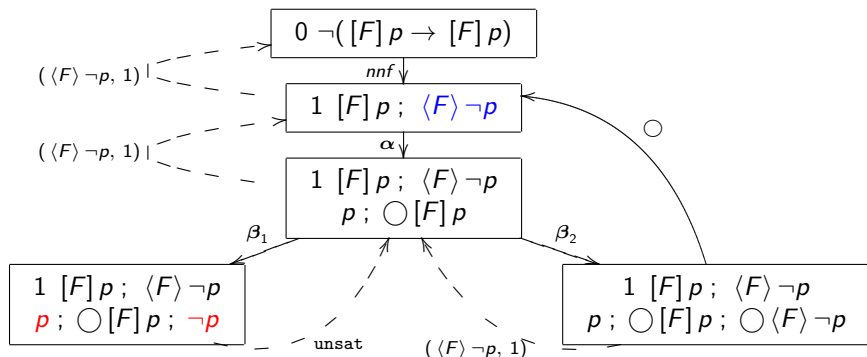


Return: extra information from children to parents

$(\langle F \rangle \neg p, j)$: eventualities that are blocked from being fulfilled and the height of their blocking ancestor **exor** $unsat$ to indicate “closed”

Tree-tableau method for LTL

Use the tree-tableaux for modal logics, with ancestor loops:



Closure: node at level i receives back a pair (ev, j) where $j > i$

Hence: node 0 closes itself, thus closing the tableau

Reason: $\langle F \rangle \neg p$ not fulfilled by the subtree rooted at node 1

Properties of one-pass tree tableaux for LTL

Thm: φ is glc of \mathcal{T} iff **any** one-pass tree-tableau for $\mathcal{T} \cup \neg\varphi$ closes

Complexity worst-case: 2^{EXPTIME} close all branches

Complexity best-case: less first branch is open

Space: worst-case is EXPSPACE depth-first search

Advantage: may avoid unnecessary work

Example: $\langle F \rangle \varphi \wedge \langle F \rangle \Psi$ where Ψ is huge but irrelevant

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What about CTL and PDL?

How to regain optimality?

Extensions to handle CTL and PDL

Replace $(\bigcirc) \frac{\bigcirc\varphi; \bigcirc X; \Lambda}{\varphi; X} \dagger$ by appropriate rules

CTL: models use branching-time

$$(\text{EX}) \frac{EX\varphi_1; EX\varphi_2; \dots; EX\varphi_k; AX Y; \Lambda}{\varphi_1; Y; \mathcal{T} \parallel \varphi_2; Y; \mathcal{T} \parallel \dots \parallel \varphi_k; Y; \mathcal{T}} \dagger$$

Eventualities: now there are two

$E(\varphi \mathcal{U} \psi)$: β -rule uses $\min(i, j)$ to track “longest” loop as for LTL

$A(\varphi \mathcal{U} \psi)$: β -rule uses $\max(i, j)$ to track “shortest” loop

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Eventualities: now there are two

$E(\varphi U \psi)$: β -rule uses $\min(i, j)$ to track “longest” loop as for LTL

$A(\varphi U \psi)$: β -rule uses $\max(i, j)$ to track “shortest” loop

PDL: branching and-rule but only eventuality is $\langle \alpha^* \rangle \varphi$

regular expressions tracked using extra annotations in each node

Complexity: Still suboptimal ... how to regain optimality?

One-Pass Tableaux for Computation Tree Logic. LPAR 2007

An On-the-fly Tableau-based Decision Procedure for PDL-Satisfiability.

M4M 2007

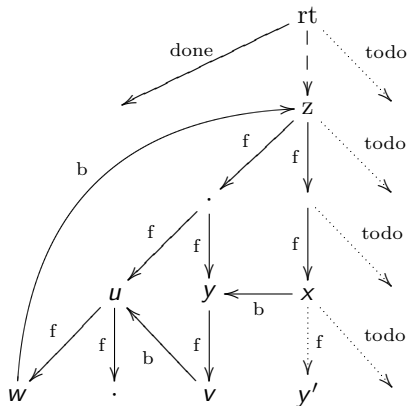
On-the-fly And-Or Graph Tableaux for LTL and PDL

Interleave: the graph building and graph pruning phases

Global Caching: allow cross branch edges to previous node copies

Advantage: complexity optimal

Disadvantage: requires more memory



On-the-fly And-Or Graph Tableaux for LTL and PDL

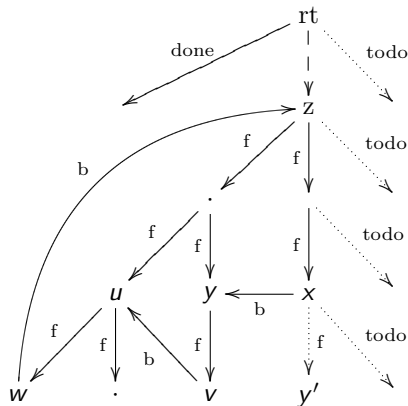
Fulfilled: in the graph to the left of the frontier

Potentially fulfillable: path from x always procrastinates but hits a forward-ancestor of x on the current branch

e.g. the path x, y, v, u, w, z

potential rescuers

Closed: unfulfilled and unfulfillable



Theorems for LTL and PDL only

Thm: `root.status = unsat` implies $\Gamma \cup \{\neg\varphi\}$ is L-unsatisfiable

Proof: not trivial

Thm: `root.status = sat` implies $\Gamma \cup \{\neg\varphi\}$ is L-satisfiable

Proof: not trivial

Thm: Worst-case complexity is EXPTIME

Proof: in worst case, we explore 2^n different (annotated) nodes

To Do: we could not find a way to handle the $A(\varphi U \psi)$ eventuality of CTL using on-the-fly and-or graph tableaux

An Optimal On-the-Fly Tableau-Based Decision Procedure for PDL-Satisfiability. CADE 2009

Handling Converse in Modal And-Or Tableaux

Let us go right back to and-or modal tableaux and add converse

$$(id) \frac{p; \neg p; X}{\quad} \quad (\wedge) \frac{\varphi \wedge \psi; X}{\varphi; \psi; X} \quad (\vee) \frac{\varphi \vee \psi; X}{\varphi; X \mid \psi; X}$$

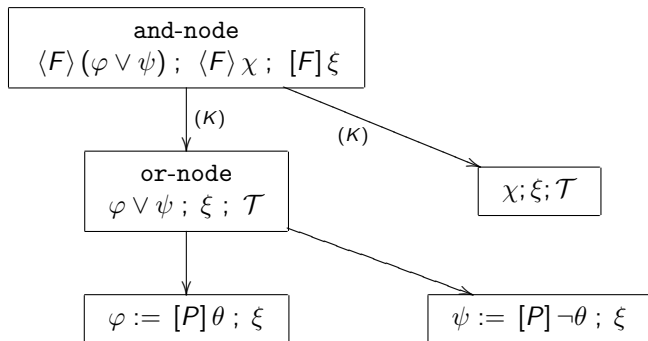
$$(K) \frac{\langle \rangle \varphi_1; \langle \rangle \varphi_2; \cdots; \langle \rangle \varphi_k; \Box X; Z}{\mathcal{T}; \varphi_1; X \parallel \mathcal{T}; \varphi_2; X \parallel \cdots \parallel \mathcal{T}; \varphi_k; X} \dagger$$

Converse Operator Can Cause Incompatibility

Converse: add box and diamond connectives w.r.t. R^{-1}

Syntax: two copies $[F]$ for Future and $[P]$ for Past of $[]$

Axioms: $\varphi \rightarrow [F] \langle P \rangle \varphi$ $\varphi \rightarrow [P] \langle F \rangle \varphi$

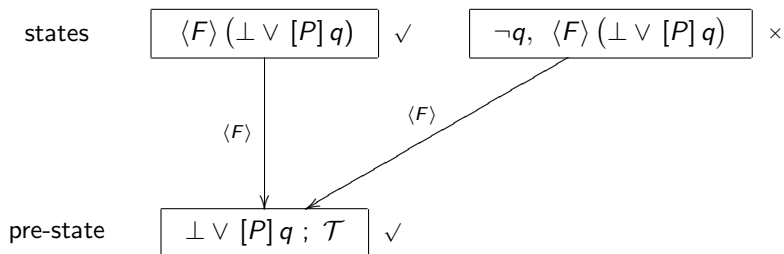


Usual solution: “restart”, requires “dynamic blocking” and is suboptimal

Global Caching Not Possible

Node with no top-level conjunctions or disjunctions is a state

Non-states are pre-states



Satisfiability of pre-state does not imply satisfiability of state

Our Alternative Method

Starting point: “Sound Global Caching for *ALC*” from DL07

Node contents fixed: at its creation \leadsto no dynamic blocking

New status type: unexpanded, sat, unsat, open, *toosmall*

Dynamic Status: status of a node changes during the algorithm:

- ▶ Example 1: unexpanded \leadsto unsat
- ▶ Example 2: unexpanded \leadsto open \leadsto toosmall

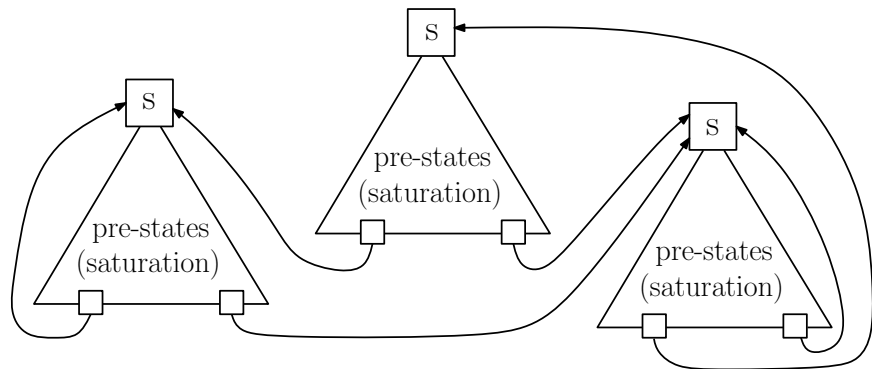
But: status of sat, unsat, or toosmall will not change

Global State Caching: never explore the same state again

Global caching: no two *nodes* with the same set of formulae

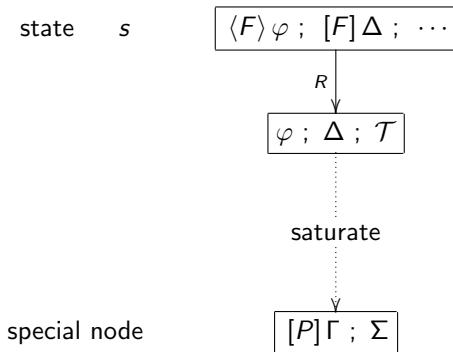
Global state caching: no two *states* with the same set of formulae

Saturation: apply \wedge and \vee rules until not applicable (giving state)



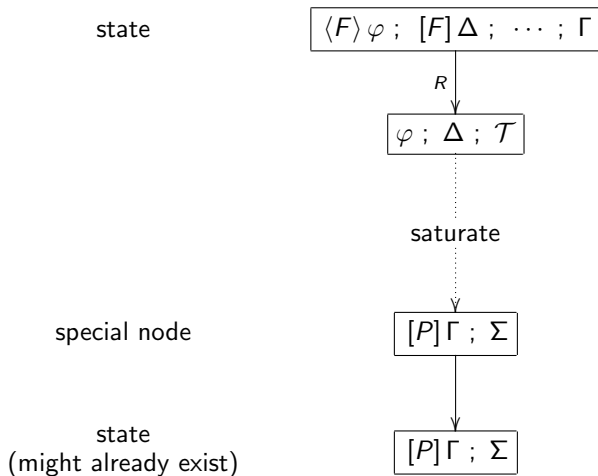
Special Nodes

Basic idea: separate a state from the saturation phase of another state.



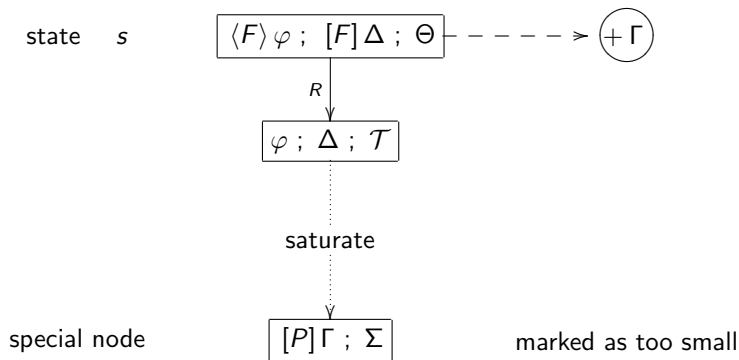
If Γ in s , the special node is *compatible* with s .

Compatible Special Nodes



Not Compatible Special Nodes

remember possible
extension Γ for s



The Algorithm: Main Loop

- ▶ Pick node x which has not been expanded yet.
- ▶ Expand x , that is create children if needed and link them appropriately.
- ▶ Determine and set the status of x from unexpanded to either open, sat, unsat, or too small (see next slides).
- ▶ Explicit update/propagation phase, activated by status change of a node

Determining the Status of And and Or Nodes

Or-nodes

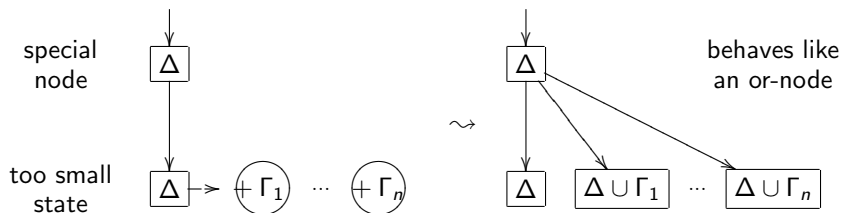
- ▶ some child is sat \rightsquigarrow or-node is sat
- ▶ else: some child is open or unexpanded \rightsquigarrow or-node is open
- ▶ else: some child is too small \rightsquigarrow or-node is too small
- ▶ else: all children unsat \rightsquigarrow or-node is unsat

And-nodes

- ▶ some child is unsat \rightsquigarrow state is unsat
- ▶ else: some child is too small \rightsquigarrow state is too small
- ▶ else: some child is open or unexpanded \rightsquigarrow state is open
- ▶ else: all children are sat \rightsquigarrow state is sat

Determining the Status of a Special Node

- ▶ child \neq too small \rightsquigarrow special node gets the same status
- ▶ state child too small with possible extensions $\Gamma_1, \dots, \Gamma_n$:



Theorems for Converse Roles

Complexity: the algorithm terminates and runs in EXPTIME

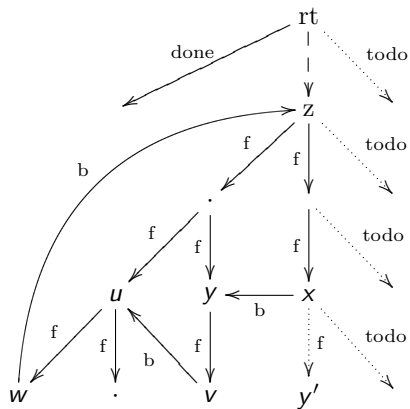
Thm: If a node is sat or remains open, its formulae are jointly satisfiable.

Thm: If a node is unsat, its formulae are not jointly satisfiable.

Thm: If the root node is too small, its formulae are not jointly satisfiable.

Sound Global State Caching for ALC with Inverse Roles.
TABLEAUX 2009

On-the-fly Complexity Optimal Tableaux for CPDL



On-the-fly Complexity Optimal Tableaux for CPDL

potential rescuers: on-the-fly graph tableaux

annotations: inside nodes to track regular expressions

special nodes: to handle converse

global state caching: to handle converse

On-the-fly Complexity Optimal Tableaux for CPDL

potential rescuers: on-the-fly graph tableaux

annotations: inside nodes to track regular expressions

special nodes: to handle converse

global state caching: to handle converse

unexp: initially all nodes have status unexpanded

undef: expanded but status not known

closed(*alt*): toosmall so needs to be cloned into alternatives

open(*prs, alt*): open with potential rescuers, and alternatives in case it is closed later on

closed(.): unsatisfiable, will never change again

idx_x: unique time stamp of when it became “defined” for proofs by induction

On-the-fly Complexity Optimal Tableaux for CPDL

Apply the following “rules” repeatedly in this order

Rule 1: picks an unexpanded node and expands it

Rule 2: picks an expanded but undefined node and computes its (initial) status. It also sets the correct time stamp.

Rule 3: picks an open node whose status has changed and recomputes its status.

Rule 4: is only applicable if all nodes are up-to-date. It picks an open node containing an eventuality φ which is currently not fulfilled in the graph and which does not have any potential rescuers either. As this indicates that φ can never be fulfilled, the node is closed.

On-the-fly Complexity Optimal Tableaux for CPDL

Soundness, Completeness and Complexity: Let $\phi \in \text{Fml}$ be a formula in negation normal form of size n . The procedure `is-sat(ϕ)` terminates, runs in EXPTIME in n , and ϕ is satisfiable iff `is-sat(ϕ)` returns true.

Implementations:

<http://users.cecs.anu.edu.au/~rpg/software.html>

Note: As far as I know, this is the only complexity-optimal algorithm for CPDL that does not use a cut rule

Optimal and Cut-Free Tableaux for Propositional Dynamic Logic with Converse. IJCAR 2010

Related Work for Fixpoint Logics

Terminating Tableaux: for LTL exist (experimentally not competitive)

Resolution Methods: LTL and CTL, optimal, PDL?, converse?

BDD-based methods: LTL, CTL, PDL plus converse, optimal

MLSolver: general solver for many modal logics

- ▶ creates and solves parity game optimally
- ▶ handles many fixpoint logics including LTL, CTL, PDL, CTL* and mu-calculus converse?
- ▶ experimentally not competitive

CTL*: Mark Renolds has developed a suboptimal tableau calculus

Mona: embed into S1S ... non-elementary complexity

PDL: automata based methods exist (converse?)

CPDL: De Giacomo and Massacci (Inf. and Comp. 2000)

- ▶ paper does not give explicit EXPTIME algorithms
- ▶ only known implementation for CPDL is unsound
- ▶ new implementation for PDL exists

Further Work

Optimisations: needed since many standard ones are not sound

Extend: to other fixpoint logics e.g. CTL, ATL, LCK

SAT: many people investigating using modern SAT/SMT solvers

QBF: worth investigating instead of SAT solvers

Efficiency and Scalability: is the front line

Questions?